



U.S. Army Research, Development and Engineering Command



Brown Deer  
Technology

High Performance  
Java

**ARL**

**TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.**

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Song J. Park, Dale R. Shires, Brian J. Henz  
September 11, 2012

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- ▶ Context
- ▶ Java
- ▶ Aparapi
- ▶ Conclusion
- ▶ Questions

Software Goals:

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- ▶ Compatibility

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- ▶ Reusability
- ▶ Usability



# Introduction



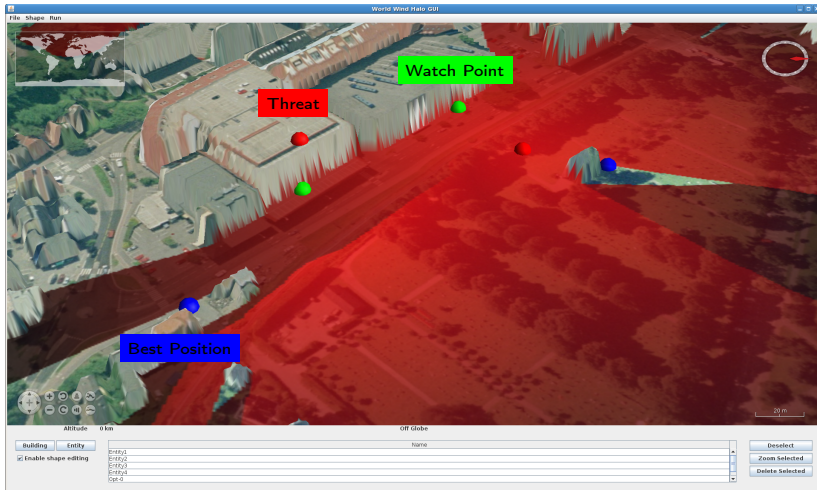
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*TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.*

"For over a decade prophets have voiced the contention that the organization of a single computer has reached its limits and that truly significant advances can be made only by interconnection of a multiplicity of computers." - Gene Amdahl

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"We stand at the threshold of a many core world. The hardware community is ready to cross this threshold. The parallel software community is not." - Tim Mattson

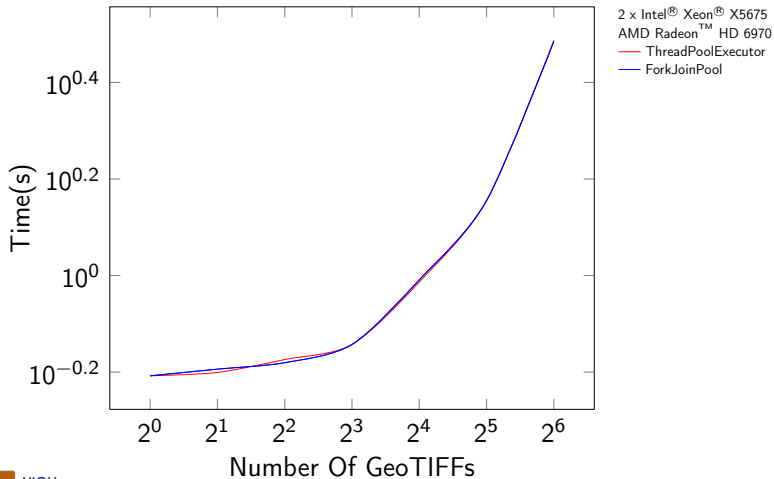


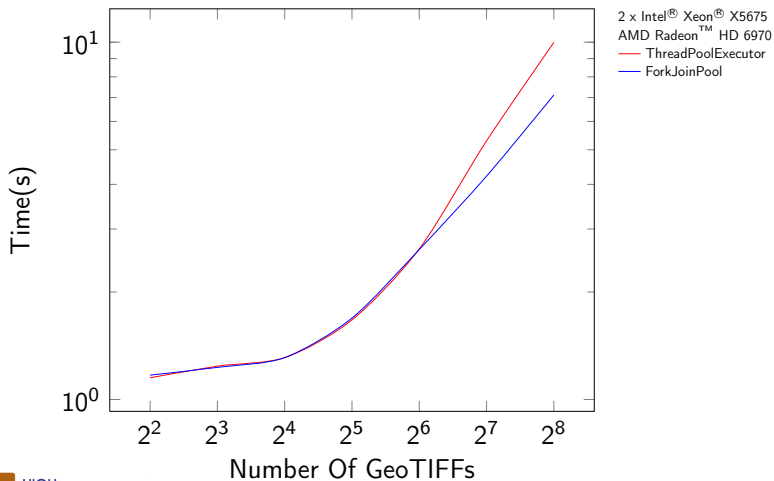
- ▶ Thread
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- ▶ ForkJoinPool
  - Java 7
  - N Concurrent Queues
  - Work-Stealing

- ▶ Load A Set Of GeoTIFFs Into A Usable Data Format
- ▶ NASA WorldWind Java Data Formats:
  - ElevationModel
  - SurfacelImage
- ▶ Performance Comparison Between ThreadPoolExecutor And ForkJoinPool







- ▶ Central Processing Units (CPUs)
- ▶ Graphics Processing Units (GPUs)
- ▶ Field-Programmable Gate Arrays (FPGAs)
- ▶ Digital Signal Processors (DSPs)
- ▶ Microcontrollers

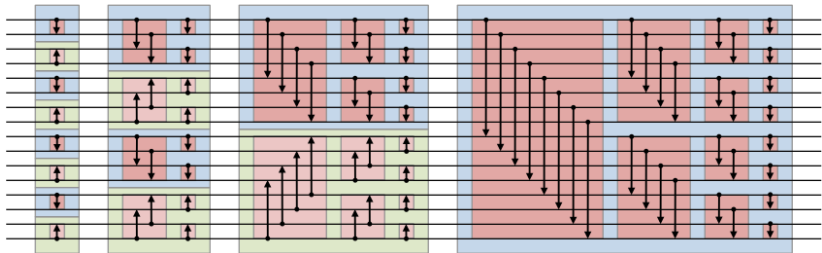
- ▶ JCuda
- ▶ [jocl.org](http://jocl.org) JOCL
- ▶ [JogAmp.org](http://JogAmp.org) JOCL
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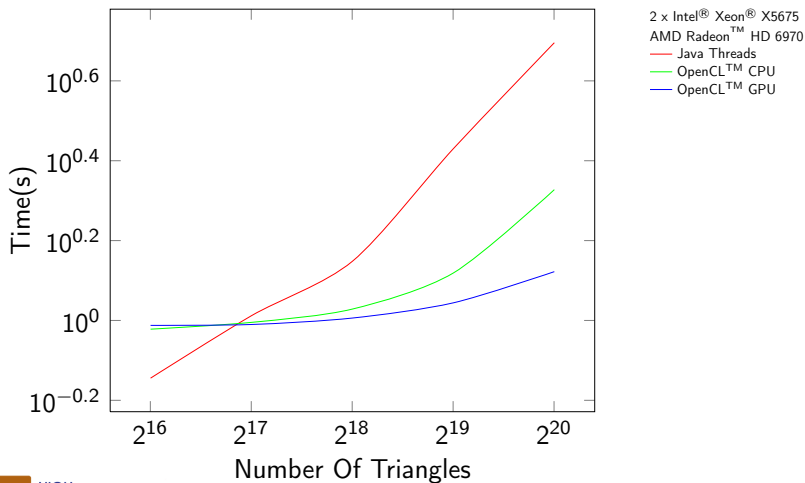
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- ▶ **Aparapi**
- ▶ Rootbeer

- ▶ Bounding Box Construction
  - $O(1)$  Parallel Time
- ▶ Bitonic Sort
  - $O(\log^2(n))$  Parallel Time



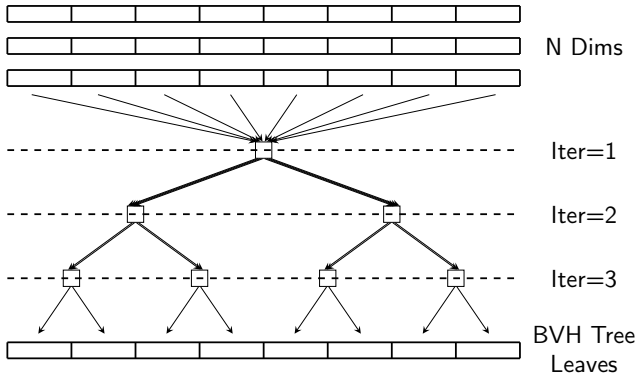
<http://upload.wikimedia.org/wikipedia/en/b/bd/BitonicSort1.svg>





► BVH Tree Construction

- $O(\log(n))$  Parallel Time
- $O(2^{iteration})$  Parallel Execution Units



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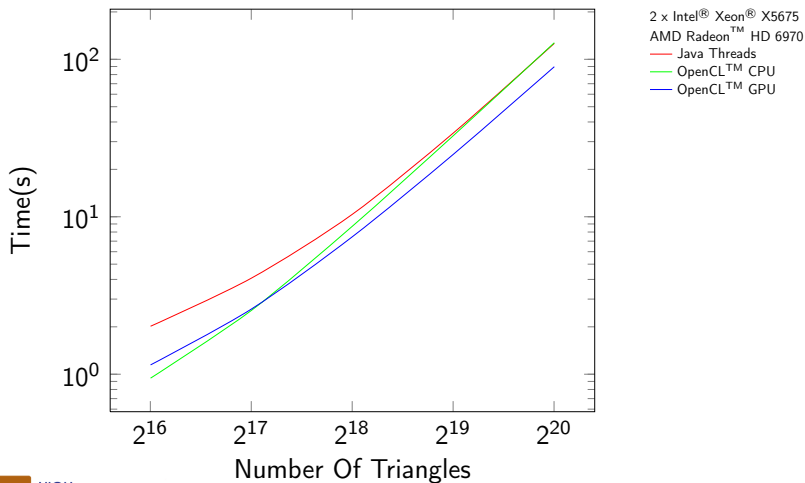
```
1: procedure BuildBVHTree
2:   SetupInitialNode
3:   while NotFullySplit do
4:     for all NodesWhichExist do
5:       for all Dimension  $\in$  Dimensions do
6:         ChooseBestSplit
7:       end for
8:       SplitNode
9:       SetupNodeForDataParallelPortion
10:      for all Dimension  $\in$  Dimensions do
11:        if DimensionWasNotSplitDimension then
12:          for all Indexes  $\in$  SortedIndexes do
13:            CalculateNewPosition
14:            Reorder
15:          end for
16:        end if
```

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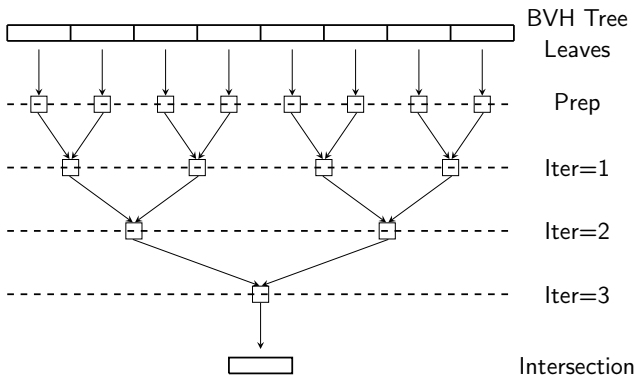
```
17:         end for
18:     end for
19: end while
20: for all Node ∈ Nodes do
21:     CalculateAxisAlignedBoundingBoxes
22: end for
23: for Values ∈ Sorted do
24:     SetToSortedIndexInFirstDimension
25: end for
26: end procedure
```

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► Intersection Kernel

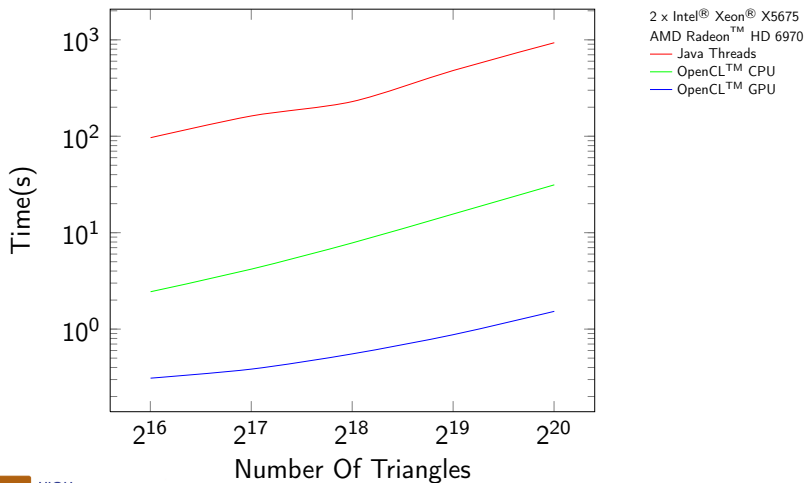
- $O(\log(n))$  Parallel Time
- $O(2^{\text{Iterations} - \text{Iteration}})$  Parallel Execution Units



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```
1: procedure IntersectBVHTree
2:   for all Ray  $\in$  Rays do in Parallel
3:     for all Node  $\in$  LeafNodes do in Parallel
4:       if RayHitsBoundingBox then
5:         FindClosestStructureHit
6:       end if
7:     end for
8:     FindClosestNodeHit
9:   end for
10: end procedure
```

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  - Pros:
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  - Cons:
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Questions?