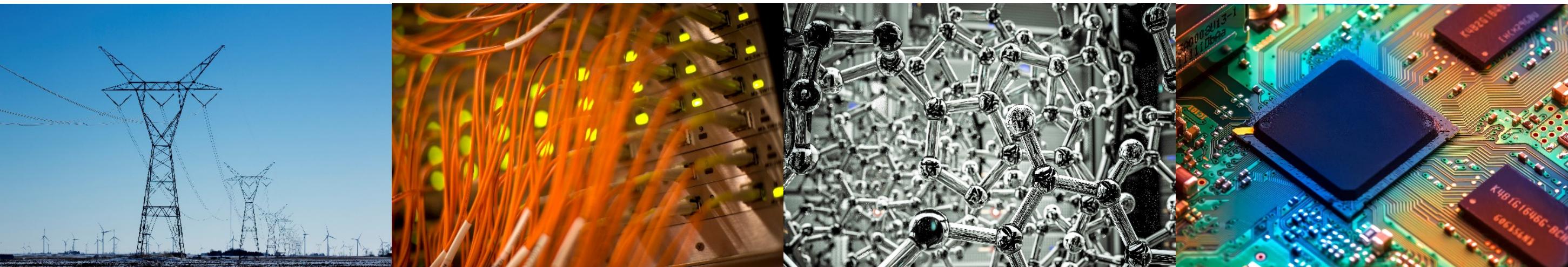


# An Efficient and Composable Parallel Task Programming Library

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Electrical & Computer Engineering

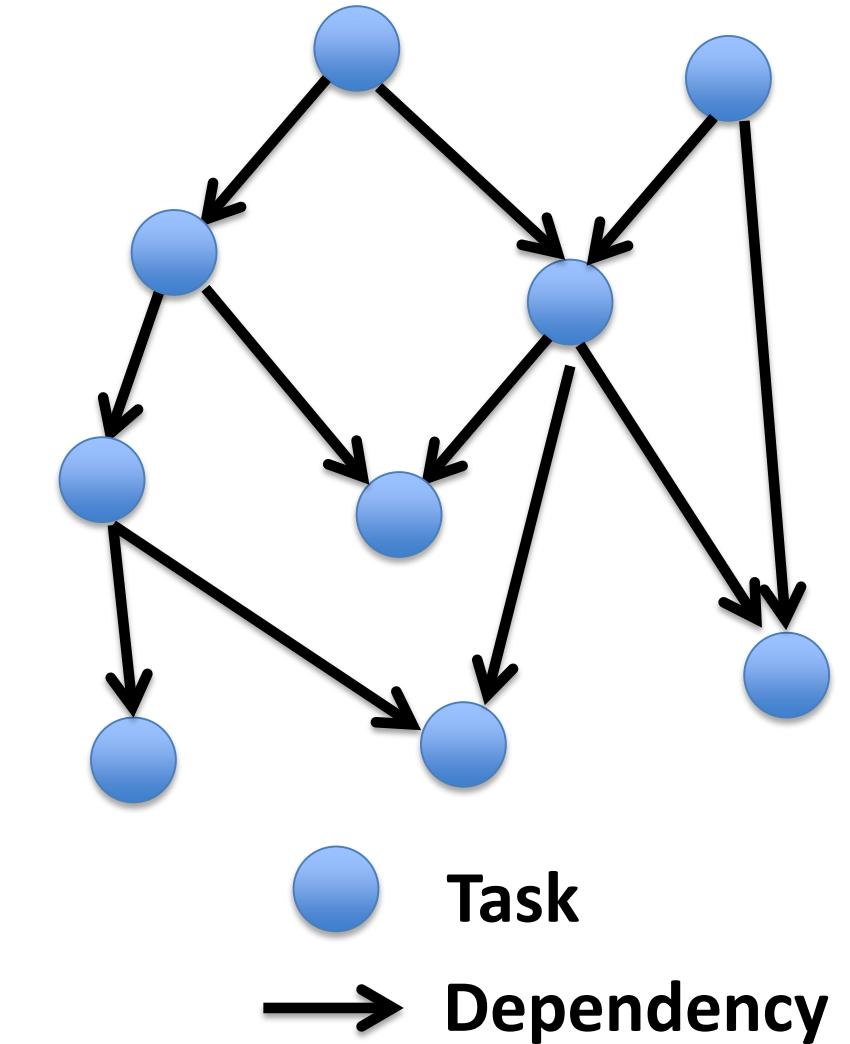
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# Outline

- Cpp-Taskflow
- Cpp-Taskflow v2
  - Task dependency graph
    - Separation of graph and executor
    - Composition
    - Modularity
  - Execution methods
- Experimental results

# Cpp-Taskflow\*

- A C++ task-based programming library
- Task-dependency graph (DAG)
- Static and dynamic tasking
- Simple and unified APIs
- Visualization



\* *Cpp-Taskflow: Fast Task-based Parallel Programming using Modern C++ in IPDPS 2019*

# Cpp-Taskflow

- Create a taskflow object
- Add tasks
- Specify dependency
- Run!

```
1 tf::Taskflow taskflow;
2
3 auto [A, B, C, D] = taskflow.emplace(
4     [] () { std::cout << "TaskA\n"; },
5     [] () { std::cout << "TaskB\n"; },
6     [] () { std::cout << "TaskC\n"; },
7     [] () { std::cout << "TaskD\n"; }
8 );
9
10 A.precede(B); // B runs after A
11 A.precede(C); // C runs after A
12 B.precede(D); // D runs after B
13 C.precede(D); // D runs after C
14
15 taskflow.wait_for_all();
```

# Cpp-Taskflow

- Dynamic tasking
- Same API as static tasking
- Detach or join mode

```
1 tf::Taskflow taskflow;
2
3 auto [A, B, C] = taskflow.emplace(
4     [] () { std::cout << "TaskA\n"; },
5     [] () { std::cout << "TaskB\n"; },
6     [] (auto &subflow) {
7         auto C1 = subflow.emplace([](){});  
[50px]         auto C2 = subflow.emplace([](){});  
[50px]         C1.precede(C2); // C2 runs after C1
8     }
9 );
10
11 A.precede(B); // B runs after A
12 A.precede(C); // C runs after A
13
14 taskflow.wait_for_all();
```

# Cpp-Taskflow

- Easy to use
- No complex concurrency control
- Static and dynamic tasking
- Issues:
  - A task graph can only be executed once
  - **No separate** task graphs. All task graphs are stored in a single taskflow object.

# Cpp-Taskflow v2

- Separate executor and task graph



Make sure task graphs persist during execution

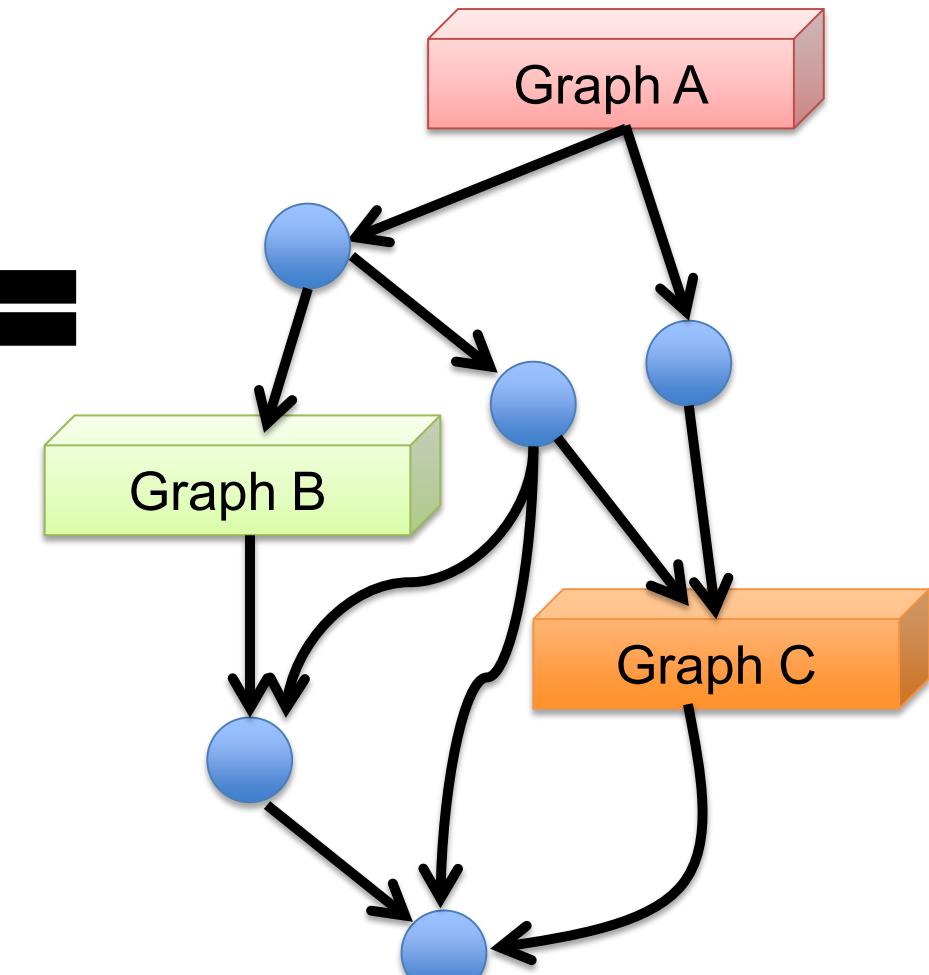
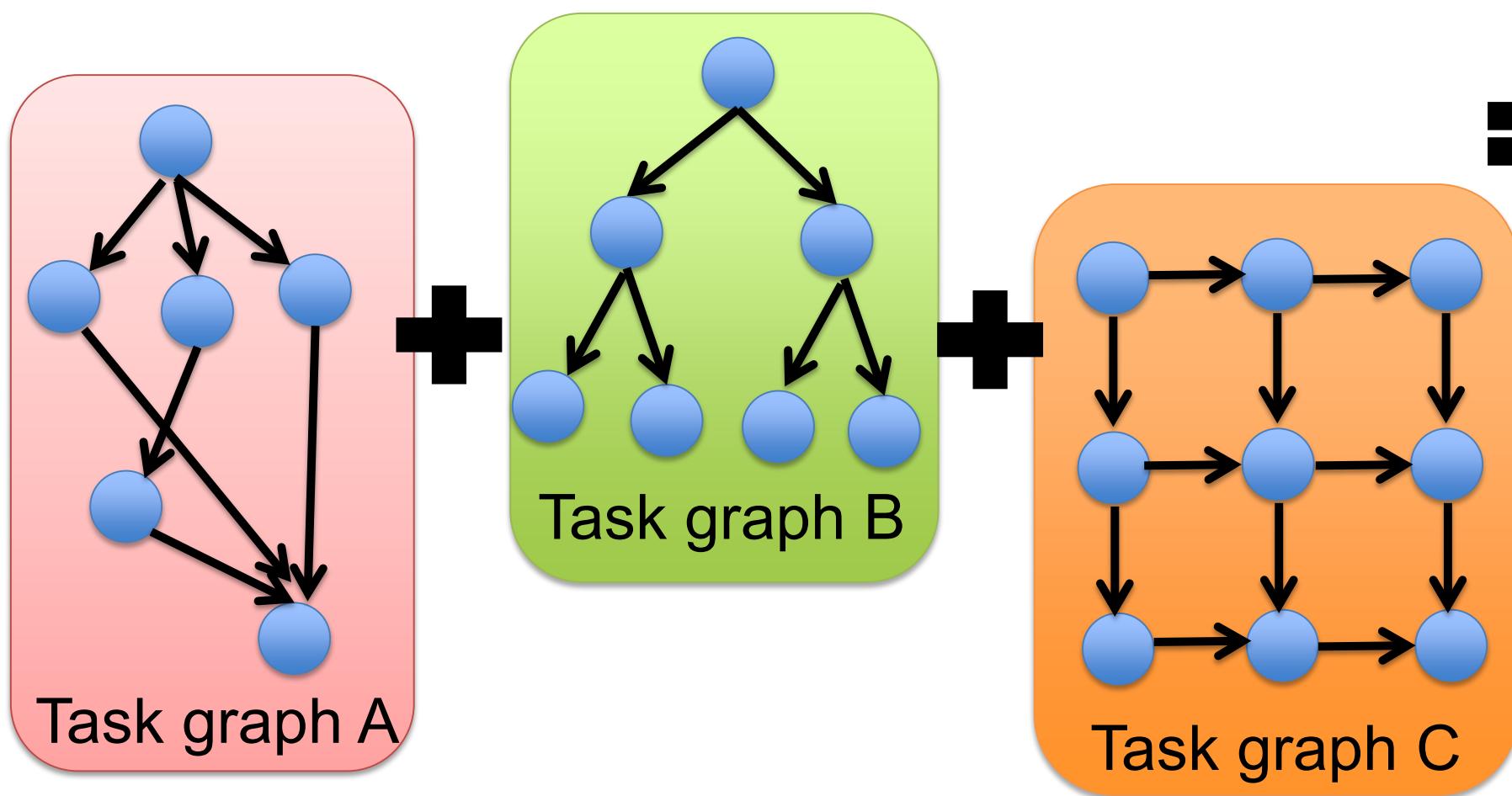
```
1 tf::Taskflow flow;
2 auto t1 = flow.emplace([](){}); 
3 auto t2 = flow.emplace([](){}); 
4 t1.precede(t2);
5
6 tf::Taskflow flow2;
7 auto t3 = flow2.emplace([](){}); 
8 auto t4 = flow2.emplace([](){}); 
9 t3.precede(t4);
10
11 tf::Executor executor;
12 executor.run(flow);
13 executor.run(flow2);
14 executor.wait_for_all();
```

Create task graphs independent to each other

Create an executor to run the graph in any order!

# Cpp-Taskflow v2

- Task graph composition



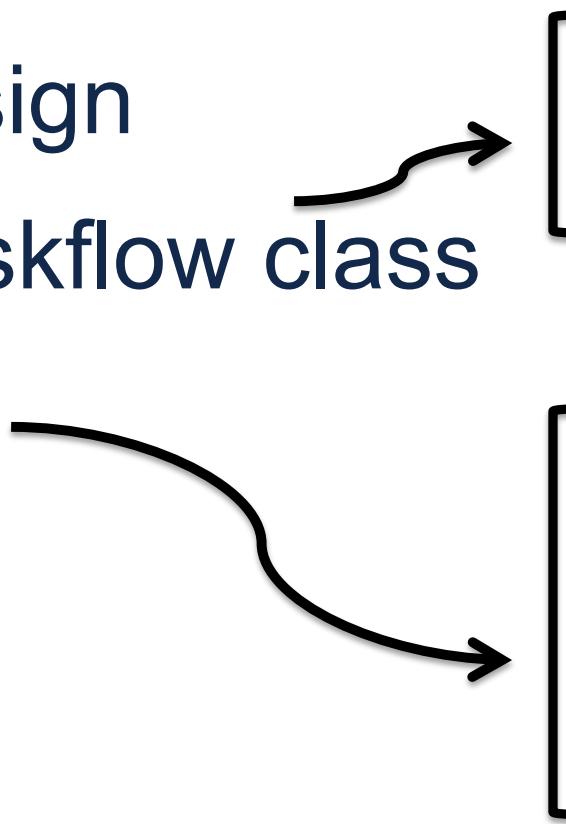
# Cpp-Taskflow v2

- Task graph composition
- API: **composed\_of**
- Seamless integration with existing task interface
- A task graph can be composed many times.

```
1  tf::Taskflow flow;
2  auto t1 = flow.emplace([](){});  
3  auto t2 = flow.emplace([](){});  
4  t1.precede(t2);  
5  
6  tf::Taskflow flow2;  
7  auto t3 = flow2.emplace([](){});  
8  auto t4 = flow2.emplace([](){});  
9  
10 // Composition
11 auto t5 = flow2.composed_of(flow);
12 t5.precede(t3, t4);
13
14 tf::Executor executor;
15 executor.run(flow2).wait();
```

# Cpp-Taskflow v2

- Modularity
- Object-oriented design
- Inheritance from taskflow class
- Same tasking APIs



```
1 struct MyGraph: tf::Taskflow {  
2     // Define your own graph  
3 }  
4  
5 MyGraph G;  
6  
7 auto t1 = G.emplace([](){});  
8 auto t2 = G.emplace([](){});  
9 t1.precede(t2);  
10  
11 tf::Executor executor;  
12 executor.run(G).wait();  
13
```

# Cpp-Taskflow v2

- Task graph is reusable
- A rich set of execution methods
  - Run once
  - Run multiple times
  - Run until a predicate is met
  - Block until all graphs finish
  - All methods return a future object

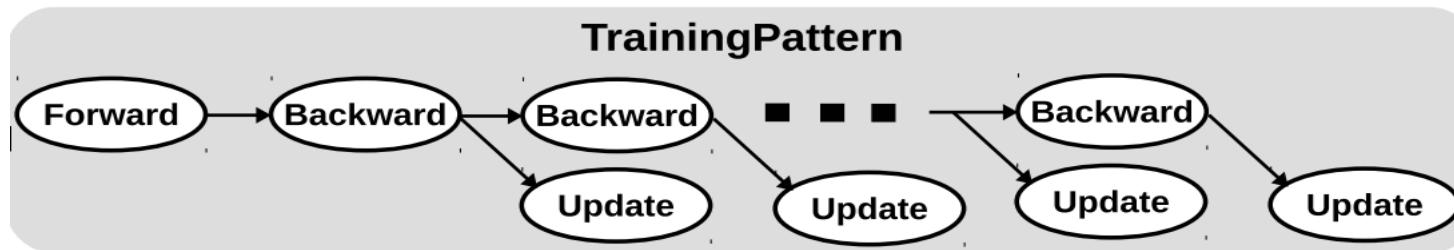
```
1 tf::Taskflow flow;
2 auto t1 = flow.emplace([](){});  
3 auto t2 = flow.emplace([](){});  
4 t1.precede(t2);  
5  
6 tf::Executor executor;  
7 // Run once  
8 executor.run(flow).wait();  
9  
10 // Run five times  
11 executor.run_n(flow, 5).wait();  
12  
13 // Run until a predicate is met  
14 executor.run_until(flow,  
15 [counter=4](){ return --counter == 0; }  
16 ).wait();
```

# Experiments

- A machine learning example
- A VLSI timing example
- Platform
  - 2.5 GHz Intel Xeon W-2175 with 14 cores
  - OS: Ubuntu 18.04
  - Compiler: GCC 7.4
- Comparison: Intel Threading Building Blocks Flow Graph

# Experiments

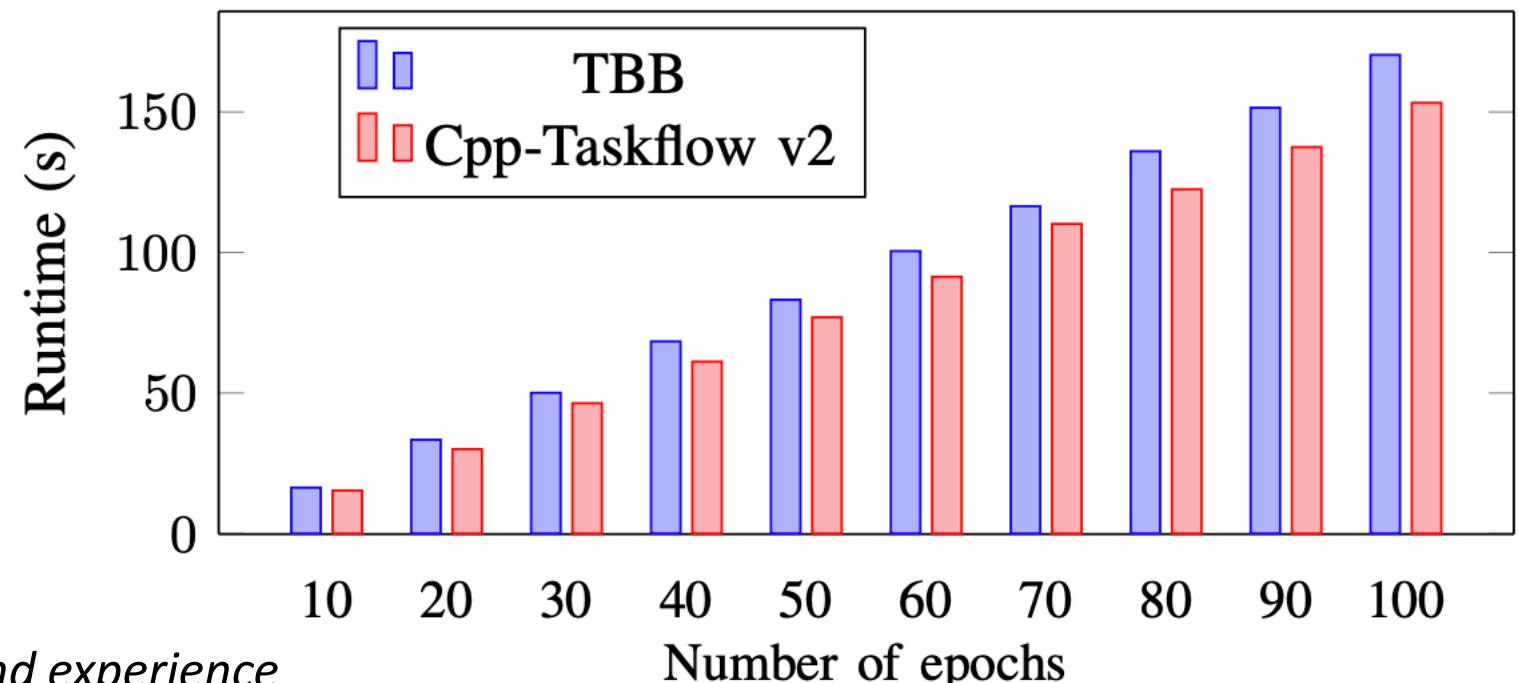
- Training 10 DNNs for MNIST dataset
- Task pipelining
- Use 10 cores



Library	NLOC (total)	CCN (avg)	Token (avg)
Cpp-Taskflow v2	60	2.0	90.6
TBB	77	2.8	125.0

NLOC: lines of code. CCN: cyclomatic complexity number.

Code complexity measured by Lizard\*



\*C++ software quality in the ATLAS experiment: tools and experience

# Experiments

- VLSI timing analysis
- Launch multiple timers (*fork*) to do timing analysis and then find the correlations between the results

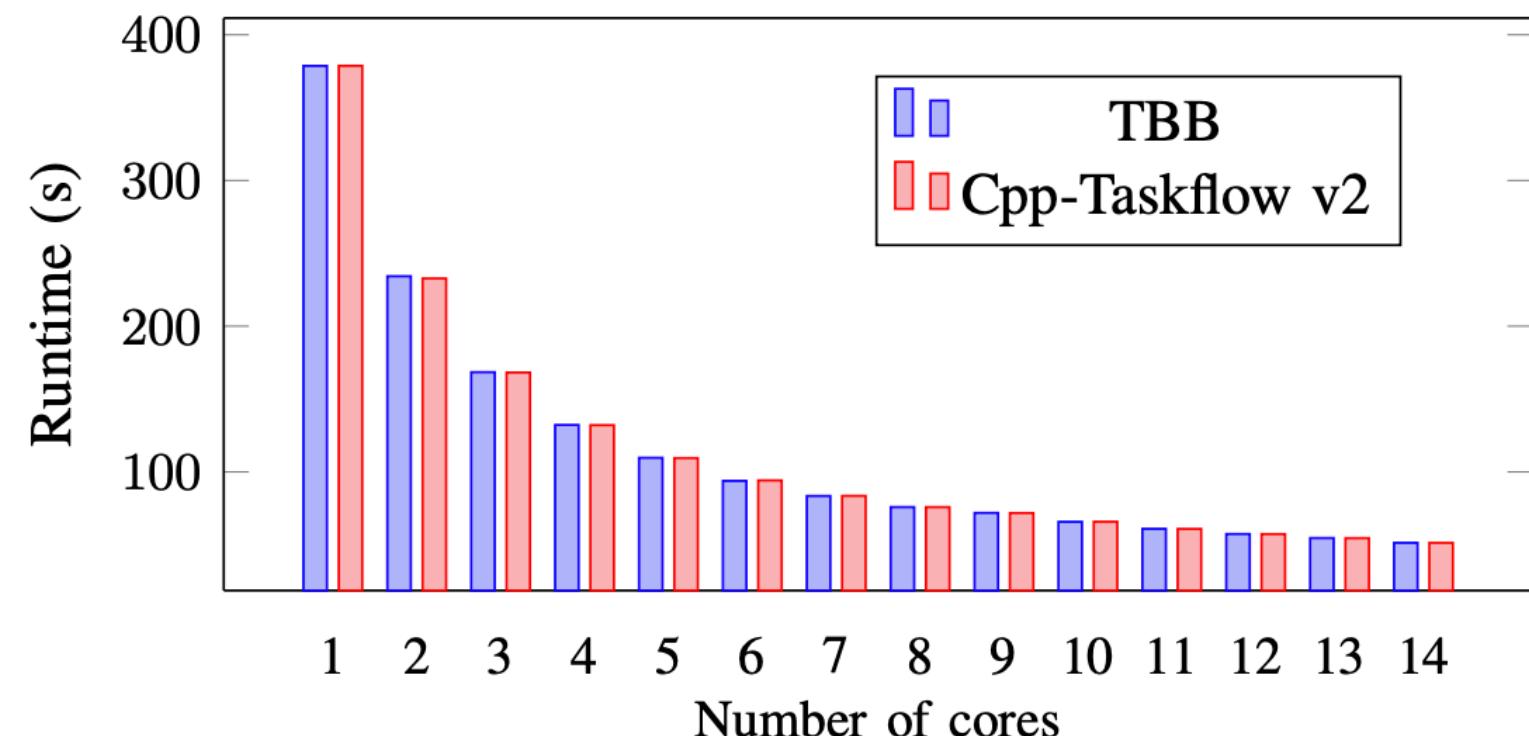
Library	NLOC (total)	CCN (avg)	Token (avg)
Cpp-Taskflow v2	61	3.0	132
TBB	104	2.6	106.6

Framework	NLOC (total)		CCN (avg)		Token (avg)	
	TF	TBB	TF	TBB	TF	TBB
Process	10	14	2	2	118	155
Simulation	5	9	2	2	47	63
Scenario	15	16	4	4	137	155
Top	23	29	4	4	226	283

NLOC: lines of code.

CCN: cyclomatic complexity number.

Code complexity measured by Lizard



# Thank You!

GitHub: <https://github.com/cpp-taskflow/cpp-taskflow>

Tutorial: <https://cpp-taskflow.github.io/>

Documentation: <https://cpp-taskflow.github.io/cpp-taskflow/>